

# Final Flexformer / Encoder–Decoder / GP–KRR / PDE Framework Report

MMNN certified benchmark synthesis

July 2, 2026

## 1 Status

Item	Status	Evidence
Frozen decoder certificates	verified	GP violations $0.0e + 00$ , $0.0e + 00$ ; PDE $0.0e + 00$
Finite-rank GP/KRR recast	verified	primal–dual gap $1.443e - 14$
PDE encoder–decoder recast	verified	$z$ MSE $6.136e - 08$ , $A$ rel $6.076e - 05$
Scaling sweep	verified	96 rows, max violation $0.0e + 00$
Spectra-only closure	disproved	depth-1 risks $1.5e - 33$ vs $1.1e - 01$
Joint overlap logging	verified	108 rows, reconstruction error $1.1e - 12$
Exact nonlinear finite-set dynamics	verified	$\nabla_\theta$ error $1.0e - 15$ ; $\nabla_P$ error $1.7e - 16$
Flexformer local NTK curves	verified locally	decoder $5.6e - 03$ ; GP/KRR $6.8e - 04$
Flexformer global outer-training theory	open	needs overlap/joint-law closure

## 2 Exact Frozen Optimization

$$x_{\ell+1} = x_\ell + P_\theta(d - Hx_\ell), \quad (1)$$

$$x^* = H^{-1}d, \quad e_\ell = x_\ell - x^*, \quad (2)$$

$$\boxed{e_L} = \boxed{(I - P_\theta H)^L e_0}, \quad (3)$$

$$\|e_L\|_2 \leq \|I - P_\theta H\|_2^L \|e_0\|_2. \quad (4)$$

This is exact for every frozen checkpoint and every preconditioner class tested.

## 3 Generalization Certificate

$$R_c \leq \widehat{R}_c + \sqrt{\frac{2\widehat{V}_c \log(2/\delta)}{n}} + \frac{7c \log(2/\delta)}{3(n-1)}. \quad (5)$$

## 4 Finite-Rank GP/KRR

$$z \sim \mathcal{N}(0, \Lambda), \quad f(x) = \phi(x)^\top z, \quad (6)$$

$$A = \Lambda^{-1} + \sigma^{-2} \Phi^\top \Phi, \quad d = \sigma^{-2} \Phi^\top y, \quad (7)$$

$$z_{\text{post}} = A^{-1}d, \quad (8)$$

$$k(x, x') = \phi(x)^\top \Lambda \phi(x'), \quad \phi_q^\top z_{\text{post}} = k_q^\top (K + \sigma^2 I)^{-1} y. \quad (9)$$

Best final GP method: `free_linear`, risk  $3.317e - 07$ .

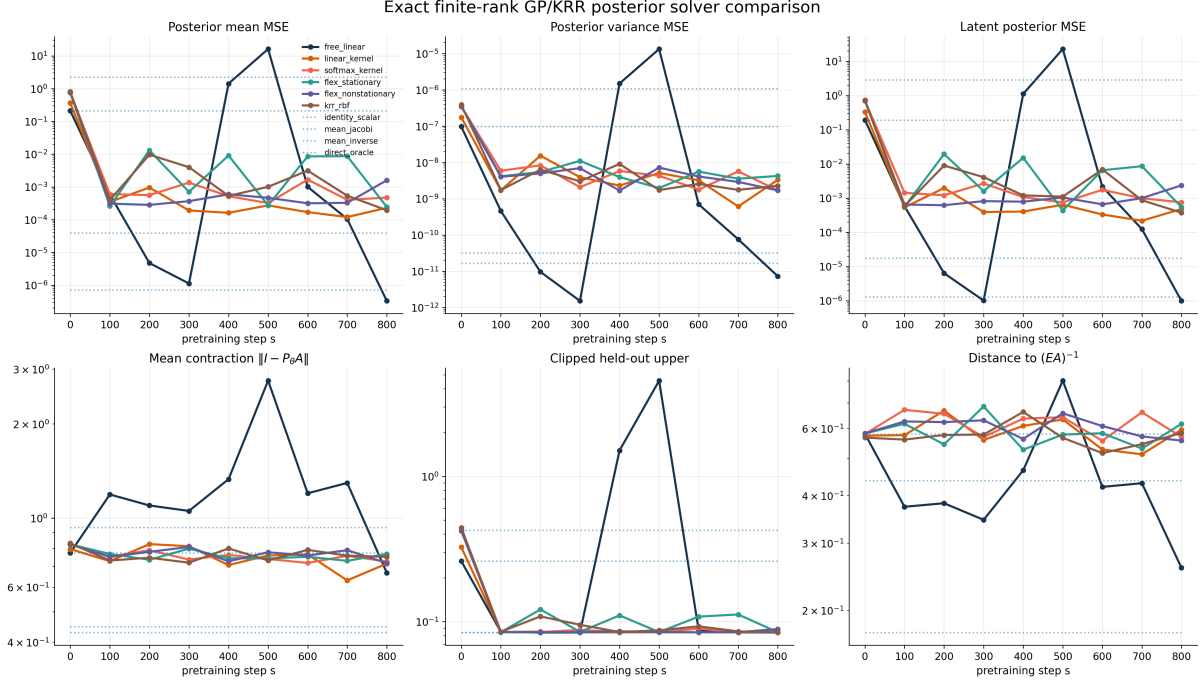


Figure 1: GP/KRR posterior framework comparison.

## 5 PDE Encoder–Decoder

$$A(z) = A_0 + \sum_{k=1}^K z_k A_k, \quad A(z)u_i = f_i, \quad (10)$$

$$G_{i,r,k} = \langle A_k u_i, v_r \rangle, \quad b_{i,r} = \langle f_i - A_0 u_i, v_r \rangle, \quad (11)$$

$$z_{\text{enc}} = (G^\top G + \lambda_z I)^{-1} G^\top b, \quad (12)$$

$$u_{\ell+1} = u_\ell + P_\theta(f_* - A(z_{\text{enc}})u_\ell). \quad (13)$$

Best final PDE method: `free_linear`, MSE  $5.976e - 06$ .

## 6 Scaling

GP prompt sizes: [16, 64]. PDE prompt sizes: [4, 16].

## 7 Spectral Closure Obstruction

$$R_L(P) = K^{-1} \text{Tr}\{(I - PH)^L S (I - PH)^{L^\top}\}. \quad (14)$$

The marginal spectrum of  $P$  is insufficient. Same eigenvalues and singular values can give different risks and training derivatives because the eigenbasis overlap with  $H, S$  differs. Eigenvalue mismatch  $0.0e + 00$ , singular-value mismatch  $4.4e - 16$ . Depth-1 risks  $1.541e - 33$  versus  $1.090e - 01$ .

$$\text{Tr}(PH), \quad \text{Tr}(PHPH), \quad \text{Tr}(PHSH^\top P^\top) \quad (15)$$

are examples of required overlap order parameters.

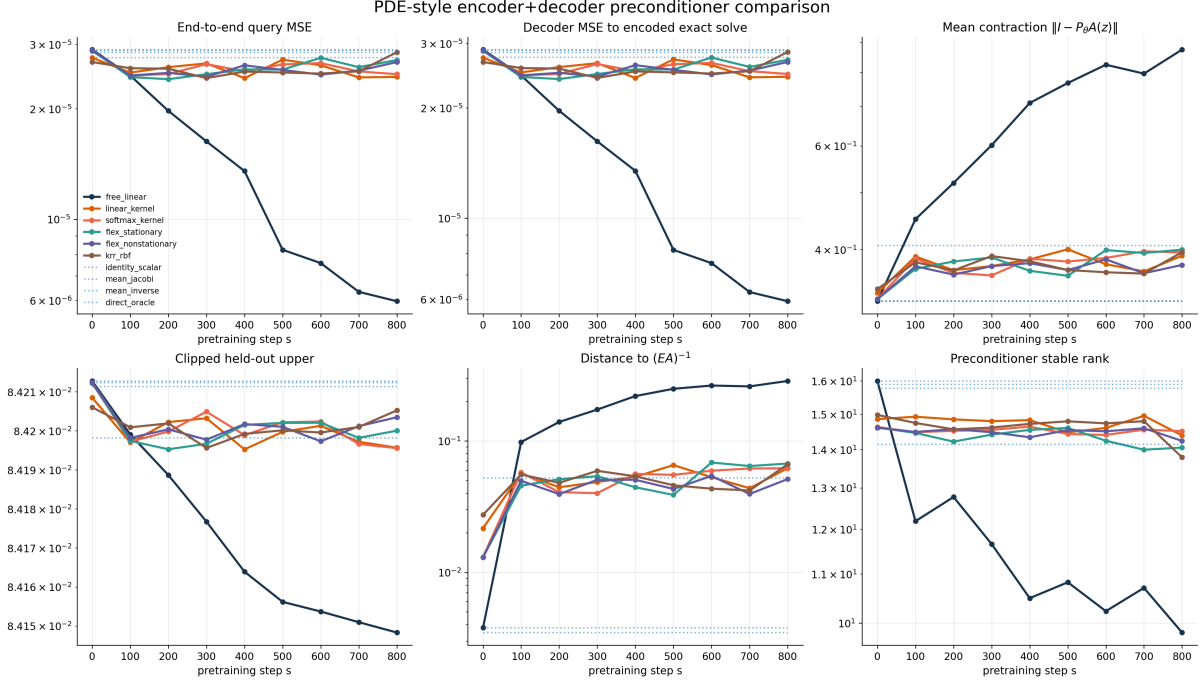


Figure 2: PDE encoder-decoder framework comparison.

## 8 Joint Order-Parameter Dynamics

For actual GP and PDE checkpoint trajectories, the logged overlap state verifies

$$R_L(P) = K^{-1} \mathbb{E} \|(I - PH)^L x^*\|^2. \quad (16)$$

Rows: 108. Maximum reconstruction absolute error:  $1.137e - 12$ . Maximum bound violation rate:  $0.0e + 00$ .

$$\text{Tr}(P\bar{H})/K, \quad \text{Tr}(P\bar{H}P\bar{H})/K, \quad \text{Tr}(P\bar{H}\bar{S}\bar{H}^\top P^\top)/K. \quad (17)$$

## 9 Flexformer Training Dynamics

$$A_\theta(i, j) = \frac{k_\theta(q_i, k_j)}{\sum_a k_\theta(q_i, k_a)}, \quad P_\theta = D_a A_\theta D_v + D_s, \quad (18)$$

$$\mathcal{L}(\theta) = \mathbb{E} \|x_L(P_\theta) - x^*\|^2. \quad (19)$$

The frozen certificate is exact. The global nonlinear outer-training dynamics are not closed by the quadratic free- $P$  theory. For a fixed finite training set, the exact nonlinear parameter

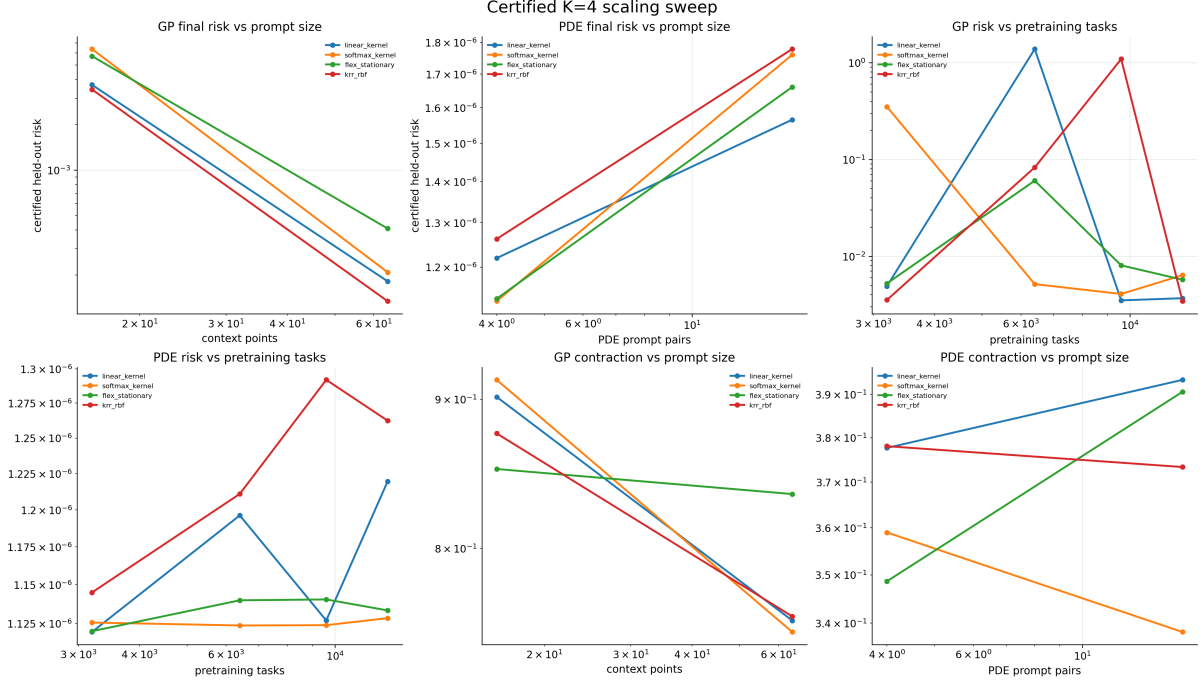


Figure 3: Certified K=4 scaling sweep.

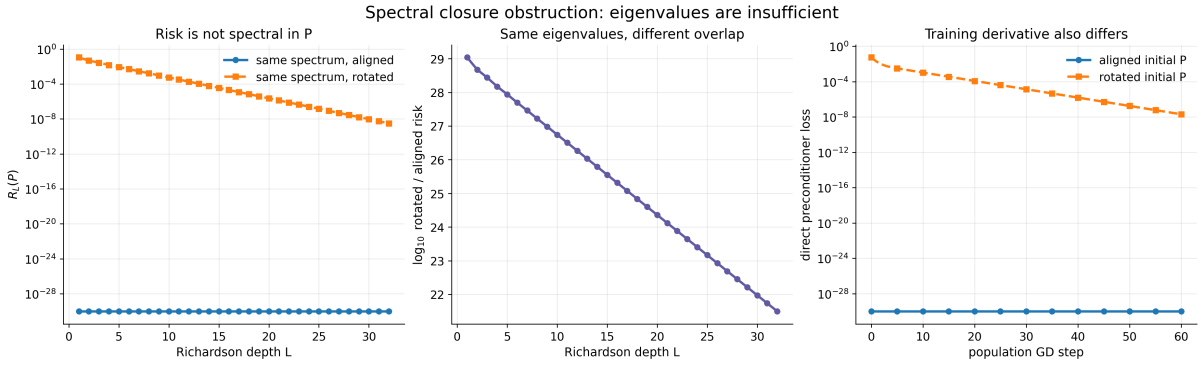


Figure 4: Spectra-only closure obstruction.

recursion is

$$z_{i,0} = 0, \quad r_{i,\ell} = d_i - H_i z_{i,\ell}, \quad z_{i,\ell+1} = z_{i,\ell} + P_\theta r_{i,\ell}, \quad (20)$$

$$\mathcal{L}_N(\theta) = \frac{1}{2NK} \sum_{i=1}^N \|z_{i,L}(P_\theta) - z_i^*\|_2^2, \quad (21)$$

$$\lambda_{i,L} = \frac{z_{i,L} - z_i^*}{NK}, \quad \lambda_{i,\ell} = (I - P_\theta H_i)^\top \lambda_{i,\ell+1}, \quad (22)$$

$$\nabla_P \mathcal{L}_N(P_\theta) = \sum_{i=1}^N \sum_{\ell=0}^{L-1} \lambda_{i,\ell+1} r_{i,\ell}^\top, \quad (23)$$

$$\theta_{s+1} = \theta_s - \eta DP_{\theta_s}^* [\nabla_P \mathcal{L}_N(P_{\theta_s})]. \quad (24)$$

Exact-gradient validation: dense- $P$  relative error  $1.727e - 16$ , parameter-gradient relative error  $1.048e - 15$ .

$$r_s^{\text{NTK}} = \left( I - \eta J_0 J_0^\top / m \right)^s r_0, \quad \mathcal{L}_s^{\text{NTK}} = \frac{1}{2m} \|r_s^{\text{NTK}}\|_2^2. \quad (25)$$

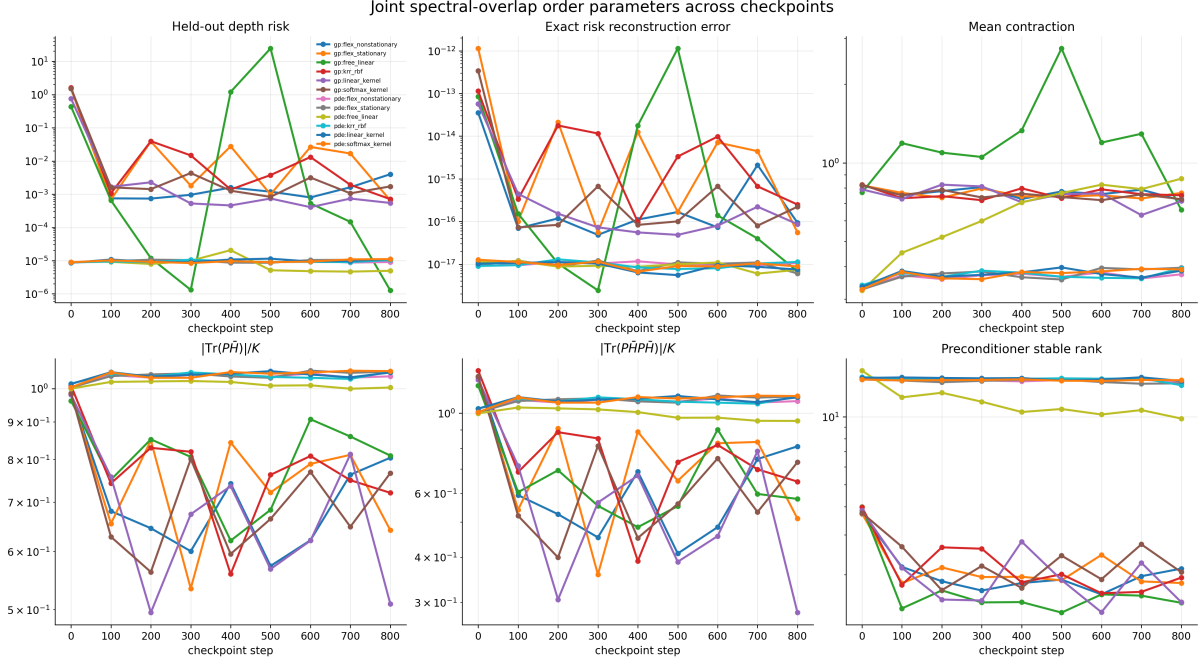


Figure 5: Joint spectral-overlap order parameters along checkpoint trajectories.

Positive-control NTK relative error:  $5.572e - 03$ . Longer local run:  $1.906e - 02$ . For finite-rank GP/KRR posterior training, the checked local model is

$$f_\theta = (z_L(P_\theta; A_i, d_i))_{i=1}^N, \quad y = (z_{\text{post},i})_{i=1}^N, \quad (26)$$

$$r_s^{\text{NTK}} = \left( I - \eta J_0 J_0^\top / m \right)^s r_0. \quad (27)$$

GP/KRR Flexformer NTK relative error:  $6.829e - 04$ . Local-diagnostic held-out posterior mean MSE:  $7.309e + 00$ .

## 10 Audit Conclusion

Achieved: exact frozen certificates, finite-rank GP/KRR recast, PDE encoder–decoder recast, K=4 CPU comparisons, scaling plots, checkpointed runs, GPU launchers. Not achieved: exact global replica/mean-field closed form for nonlinear Flexformer outer training. Spectra-only closure is insufficient; an exact closure must include overlap/joint-law order parameters.

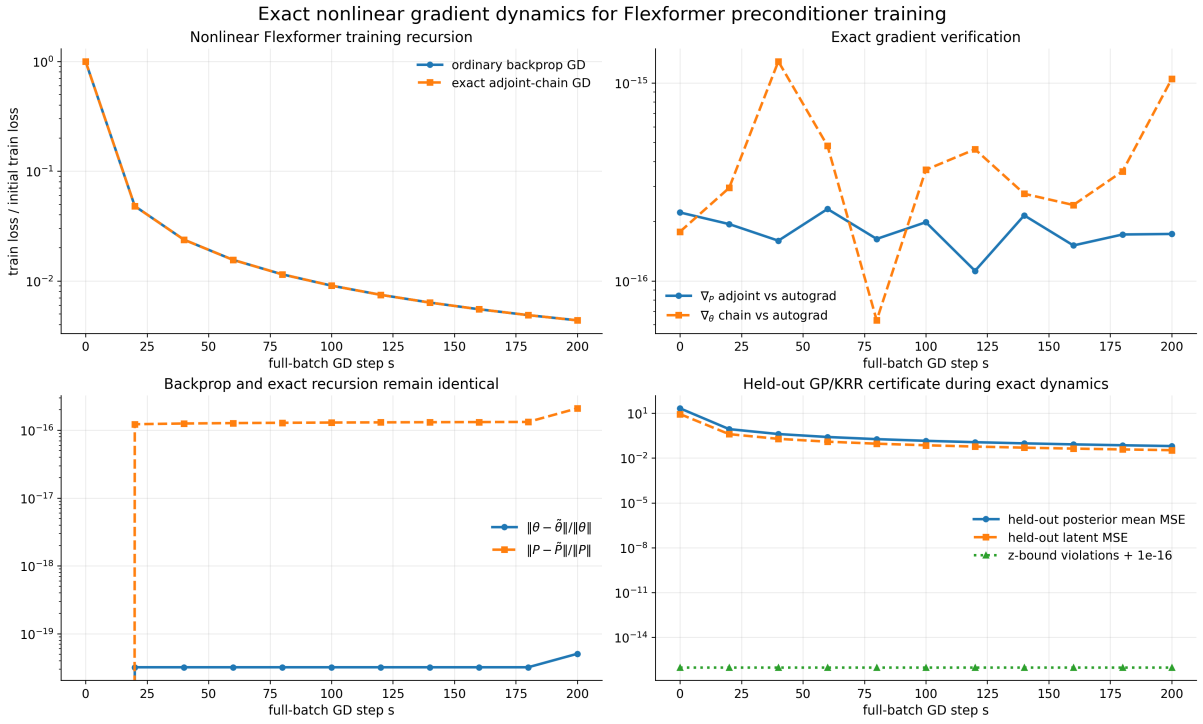


Figure 6: Exact nonlinear finite-set Flexformer gradient dynamics.

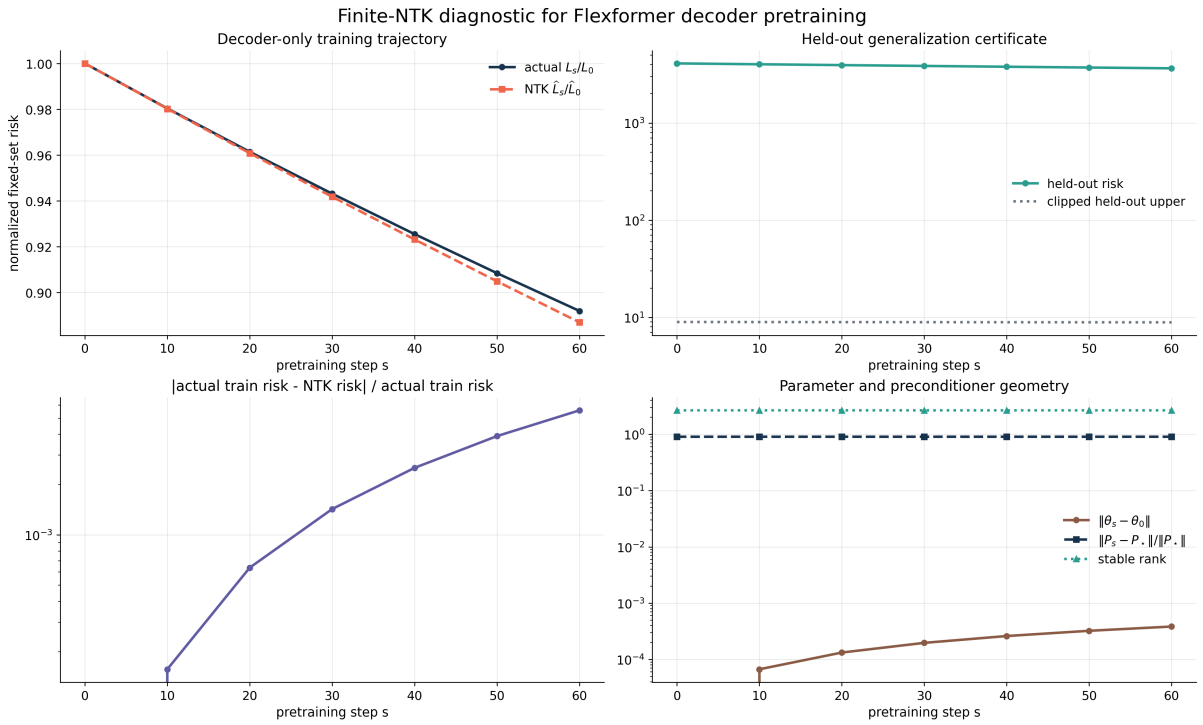


Figure 7: Finite-NTK positive-control curve.

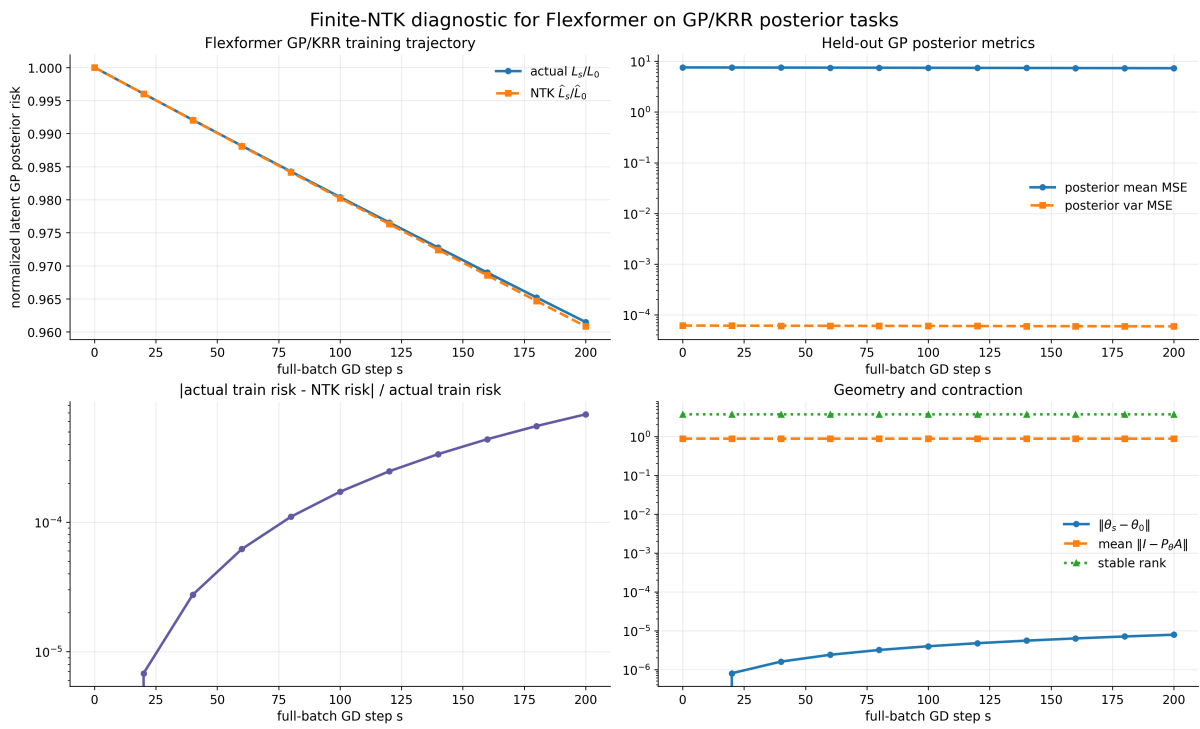


Figure 8: Finite-NTK curve for Flexformer preconditioner training on the GP/KRR posterior latent solve.